Chapter 2 — Instructions: Language of the Computer

Instruction Set
- The repertoire of instructions of a computer
- Different computers have different instruction sets
  - But with many aspects in common
- Early computers had very simple instruction sets
  - Simplified implementation
- Many modern computers also have simple instruction sets

The MIPS Instruction Set
- Used as the example throughout the book
- Stanford MIPS commercialized by MIPS Technologies (www.mips.com)
- Large share of embedded core market
  - Applications in consumer electronics, network/storage equipment, cameras, printers, ...
- Typical of many modern ISAs
  - See MIPS Reference Data tear-out card, and Appendixes B and E

Arithmetic Operations
- Add and subtract, three operands
  - Two sources and one destination
  - add a, b, c \# a gets b + c
  - All arithmetic operations have this form
  - Design Principle 1: Simplicity favours regularity
    - Regularity makes implementation simpler
    - Simplicity enables higher performance at lower cost

Arithmetic Example
- C code:
  \[ f = (g + h) - (i + j); \]
- Compiled MIPS code:
  - add t0, g, h \# t0 = g + h
  - add t1, i, j \# t1 = i + j
  - sub f, t0, t1 \# f = t0 - t1

Register Operands
- Arithmetic instructions use register operands
- MIPS has a 32 \times 32\text{-bit} register file
  - Use for frequently accessed data
  - Numbered 0 to 31
  - 32-bit data called a "word"
- Assembler names
  - $t0$, $t1$, ..., $t9$ for temporary values
  - $s0$, $s1$, ..., $s7$ for saved variables
- Design Principle 2: Smaller is faster
  - c.f. main memory: millions of locations
Register Operand Example

- C code:
  \[ f = (g + h) - (i + j); \]
  \[ f, \ldots, j \text{ in } s0, \ldots, s4 \]
- Compiled MIPS code:
  \[
  \begin{align*}
  \text{add } &t0, s1, s2 \\
  \text{add } &t1, s3, s4 \\
  \text{sub } &s0, t0, t1
  \end{align*}
  \]

Memory Operands

- Main memory used for composite data
- Arrays, structures, dynamic data
- To apply arithmetic operations
- Load values from memory into registers
- Store result from register to memory
- Memory is byte addressed
  - Each address identifies an 8-bit byte
- Words are aligned in memory
  - Address must be a multiple of 4
- MIPS is Big Endian
  - Most-significant byte at least address of a word
  - c.f. Little Endian: least-significant byte at least address

Memory Operand Example 1

- C code:
  \[ g = h + A[8]; \]
  \[ g \text{ in } s1, h \text{ in } s2, \text{base address of } A \text{ in } s3 \]
- Compiled MIPS code:
  \[
  \begin{align*}
  \text{lw } &t0, 32(s3) \quad \# \text{ load word} \\
  \text{add } &s1, s2, t0
  \end{align*}
  \]

Memory Operand Example 2

- C code:
  \[ A[12] = h + A[8]; \]
  \[ h \text{ in } s2, \text{base address of } A \text{ in } s3 \]
- Compiled MIPS code:
  \[
  \begin{align*}
  \text{lw } &t0, 32(s3) \quad \# \text{ load word} \\
  \text{add } &t0, s2, t0 \\
  \text{sw } &t0, 48(s3) \quad \# \text{ store word}
  \end{align*}
  \]

Registers vs. Memory

- Registers are faster to access than memory
- Operating on memory data requires loads and stores
  - More instructions to be executed
- Compiler must use registers for variables as much as possible
  - Only spill to memory for less frequently used variables
- Register optimization is important!

Immediate Operands

- Constant data specified in an instruction
  \[ \text{add } s3, s3, 4 \]
- No subtract immediate instruction
  - Just use a negative constant
    \[ \text{add } s2, s1, -1 \]
- Design Principle 3: Make the common case fast
  - Small constants are common
  - Immediate operand avoids a load instruction
### The Constant Zero
- MIPS register 0 ($\text{zero}$) is the constant 0
- Cannot be overwritten
- Useful for common operations
  - E.g., move between registers
    - \text{add $t2$, $s1$, $\text{zero}$}

### Unsigned Binary Integers
- Given an n-bit number
  \[ x = x_{n-1}2^{n-1} + x_{n-2}2^{n-2} + \cdots + x_12^1 + x_02^0 \]
- Range: 0 to $2^n - 1$
- Example
  \[ \begin{align*}
  0000 \ 0000 \ 0000 \ 0000 \ 0000 \ 0000 \ 0000 \ 1011 \_ \\
  &= 0 + \ldots + 1 \times 2^3 + 0 \times 2^2 + 1 \times 2^1 + 1 \times 2^0 \\
  &= 0 + \ldots + 8 + 0 + 2 + 1 = 11_{10}
  \end{align*} \]
- Using 32 bits
  - 0 to $4,294,967,295$

### 2s-Complement Signed Integers
- Given an n-bit number
  \[ x = -x_{n-1}2^{n-1} + x_{n-2}2^{n-2} + \cdots + x_12^1 + x_02^0 \]
- Range: $-2^{n-1}$ to $+2^{n-1} - 1$
- Example
  \[ \begin{align*}
  1111 \ 1111 \ 1111 \ 1111 \ 1111 \ 1111 \ 1111 \ 1100 \_ \\
  &= -1 \times 2^{31} + 1 \times 2^{30} + \cdots + 1 \times 2^1 + 0 \times 2^0 \\
  &= -2,147,483,648 + 2,147,483,644 = -410
  \end{align*} \]
- Using 32 bits
  - $-2,147,483,648$ to $+2,147,483,647$

### Signed Negation
- Complement and add 1
  - Complement means 1 → 0, 0 → 1
  - Add 1 to the complement
    - \text{Example: negate } +2
      - $+2 = 0000 \ 0000 \ \ldots \ 0010_2$
      - $-2 = 1111 \ 1111 \ \ldots \ 1101_2 + 1$
      - $= 1111 \ 1111 \ \ldots \ 1100_2$

### Sign Extension
- Representing a number using more bits
  - Preserve the numeric value
- In MIPS instruction set
  - \text{addi}: extend immediate value
  - \text{1b, 1h}: extend loaded byte/halfword
  - \text{beq, bne}: extend the displacement
- Replicate the sign bit to the left
  - C.f. unsigned values: extend with 0s
- Examples: 8-bit to 16-bit
  - $+2: 0000 \ 0010 \Rightarrow 0000 \ 0000 \ 0000 \ 0010$
  - $-2: 1111 \ 1110 \Rightarrow 1111 \ 1111 \ 1111 \ 1110$
Representing Instructions

- Instructions are encoded in binary
  - Called machine code
- MIPS instructions
  - Encoded as 32-bit instruction words
  - Small number of formats encoding operation code (opcode), register numbers, …
  - Regularity!
- Register numbers
  - $t0 – t7$ are reg's 8 – 15
  - $t8 – t9$ are reg's 24 – 25
  - $s0 – s7$ are reg's 16 – 23

MIPS R-format Instructions

- Instruction fields
  - op: operation code (opcode)
  - rs: first source register number
  - rt: second source register number
  - rd: destination register number
  - shamt: shift amount (00000 for now)
  - funct: function code (extends opcode)

MIPS R-format Example

```
add $t0, $s1, $s2
```

Hexadecimal

- Base 16
  - Compact representation of bit strings
  - 4 bits per hex digit

```
0 0000 4 0100 8 1000 c 1100
1 0001 5 0101 9 1001 d 1101
2 0010 6 0110 a 1010 e 1110
3 0011 7 0111 b 1011 f 1111
```

Example: eca8 6420

```
1110 1100 1010 1000 0110 0100 0010 0000
```

MIPS I-format Instructions

- Immediate arithmetic and load/store instructions
- rt: destination or source register number
- Constant: $-2^{15}$ to $+2^{15}$– 1
- Address: offset added to base address in rs

Design Principle 4: Good design demands good compromises

- Different formats complicate decoding, but allow 32-bit instructions uniformly
- Keep formats as similar as possible

Stored Program Computers

- Instructions represented in binary, just like data
- Instructions and data stored in memory
- Programs can operate on programs
  - e.g., compilers, linkers, …
- Binary compatibility allows compiled programs to work on different computers
- Standardized ISAs
Logical Operations

- Instructions for bitwise manipulation

<table>
<thead>
<tr>
<th>Operation</th>
<th>C</th>
<th>Java</th>
<th>MIPS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Shift left</td>
<td>&lt;&lt;</td>
<td></td>
<td>sll</td>
</tr>
<tr>
<td>Shift right</td>
<td>&gt;&gt;</td>
<td></td>
<td>srl</td>
</tr>
<tr>
<td>Bitwise AND</td>
<td>&amp;</td>
<td></td>
<td>and</td>
</tr>
<tr>
<td>Bitwise OR</td>
<td></td>
<td></td>
<td>or,</td>
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<tr>
<td>Bitwise NOT</td>
<td></td>
<td></td>
<td>nor</td>
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</tbody>
</table>

- Useful for extracting and inserting groups of bits in a word

Shift Operations

- shamt: how many positions to shift
- Shift left logical
  - Shift left and fill with 0 bits
  - sll by i bits multiplies by 2^i
- Shift right logical
  - Shift right and fill with 0 bits
  - srl by i bits divides by 2^i (unsigned only)

AND Operations

- Useful to mask bits in a word
  - Select some bits, clear others to 0

```
and $t0, $t1, $t2
```

```
$12 0000 0000 0000 0000 0000 1101 1100 0000
$11 0000 0000 0000 0000 0000 1110 0000 0000
$10 0000 0000 0000 0000 0000 1100 0000 0000
```

OR Operations

- Useful to include bits in a word
  - Set some bits to 1, leave others unchanged

```
or $t0, $t1, $t2
```

```
$12 0000 0000 0000 0000 0000 1101 1100 0000
$11 0000 0000 0000 0000 0011 1100 0000 0000
$10 0000 0000 0000 0000 0011 1101 1100 0000
```

NOT Operations

- Useful to invert bits in a word
  - Change 0 to 1, and 1 to 0

```
nor $t0, $t1, $zero
```

```
Register 0: always read as zero
```

```
$11 0000 0000 0000 0000 0000 0111 1111 1111
$10 1111 1111 1111 1111 1100 0011 1111 1111
```

Conditional Operations

- Branch to a labeled instruction if a condition is true
  - Otherwise, continue sequentially

```
beq rs, rt, L1
```

```
if (rs == rt) branch to instruction labeled L1;
```

```
bne rs, rt, L1
```

```
if (rs != rt) branch to instruction labeled L1;
```

```
j L1
```

```
unconditional jump to instruction labeled L1
```
Compiling If Statements

- C code:
  ```c
  if (i==j) f = g+h;
  else f = g-h;
  ```
  
  - f, g, ..., in $s0, $s1, ...

- Compiled MIPS code:
  ```asm
  bne $s3, $s4, Else
  add $s0, $s1, $s2
  j Exit
  Else: sub $s0, $s1, $s2
  Exit: ...  
  ```

  Assembler calculates addresses

Compiling Loop Statements

- C code:
  ```c
  while (save[i] == k) i += 1;
  ```
  
  - i in $s3, k in $s5, address of save in $s6

- Compiled MIPS code:
  ```asm
  Loop: sll $t1, $s3, 2
  add $t1, $t1, $s6
  lw $t0, 0($t1)
  bne $t0, $s5, Exit
  addi $s3, $s3, 1
  j Loop
  Exit: ...
  ```

Basic Blocks

- A basic block is a sequence of instructions with
  - No embedded branches (except at end)
  - No branch targets (except at beginning)

- A compiler identifies basic blocks for optimization
- An advanced processor can accelerate execution of basic blocks

More Conditional Operations

- Set result to 1 if a condition is true
  - Otherwise, set to 0

- `slt rd, rs, rt`
  - if (rs < rt) rd = 1; else rd = 0;

- `slti rt, rs, constant`
  - if (rs < constant) rt = 1; else rt = 0;

- Use in combination with beq, bne
  ```asm
  slt $t0, $s1, $s2  # if ($s1 < $s2)
  bne $t0, $zero, L  # branch to L
  ```

Branch Instruction Design

- Why not blt, bge, etc?
- Hardware for <, ≥, ... slower than =, ≠
  - Combining with branch involves more work per instruction, requiring a slower clock
  - All instructions penalized!
  - beq and bne are the common case
  - This is a good design compromise

Signed vs. Unsigned

- Signed comparison: `slt, slti`
- Unsigned comparison: `sltu, sltui`

- Example
  ```asm
  $s0 = 1111 1111 1111 1111 1111 1111 1111 1111
  $s1 = 0000 0000 0000 0000 0000 0000 0000 0001
  slt $t0, $s0, $s1  # signed
  # $t0 = 1
  ```

  ```asm
  sltu $t0, $s0, $s1  # unsigned
  # $t0 = 0
  ```

  ```asm
  # signed $t0 = 1
  ```

  ```asm
  # unsigned $t0 = 0
  ```
Procedure Calling

- Steps required
  1. Place parameters in registers
  2. Transfer control to procedure
  3. Acquire storage for procedure
  4. Perform procedure's operations
  5. Place result in register for caller
  6. Return to place of call

Register Usage

- $a0 - $a3: arguments (reg's 4 - 7)
- $v0, $v1: result values (reg's 2 and 3)
- $t0 - $t9: temporaries
  - Can be overwritten by callee
  - Must be saved/restored by callee
- $s0 - $s7: saved
- $gp: global pointer for static data (reg 28)
- $sp: stack pointer (reg 29)
- $fp: frame pointer (reg 30)
- $ra: return address (reg 31)

Procedure Call Instructions

- Procedure call: jump and link
  jal ProcedureLabel
  - Address of following instruction put in $ra
  - Jumps to target address
- Procedure return: jump register
  jr $ra
  - Copies $ra to program counter
  - Can also be used for computed jumps
  - e.g., for case/switch statements

Leaf Procedure Example

- C code:
  ```c
  int leaf_example (int g, h, i, j)
  { int f;
    f = (g + h) - (i + j);
    return f;
  }
  ```
  - Arguments g, ..., j in $a0, ..., $a3
  - f in $s0 (hence, need to save $s0 on stack)
  - Result in $v0

Leaf Procedure Example

- MIPS code:
  ```mips
  leaf_example:
  addi $sp, $sp, -4
  sw $s0, 0($sp)
  add $t0, $a0, $a1
  add $t1, $a2, $a3
  sub $s0, $t0, $t1
  add $v0, $s0, $zero
  lw $s0, 0($sp)
  addi $sp, $sp, 4
  jr $ra
  ```
  - Save $s0 on stack
  - Procedure body
  - Result
  - Restore $s0
  - Return

Non-Leaf Procedures

- Procedures that call other procedures
- For nested call, caller needs to save on the stack:
  - Its return address
  - Any arguments and temporaries needed after the call
- Restore from the stack after the call
Non-Leaf Procedure Example

- C code:
  ```c
  int fact (int n) {
    if (n < 1) return f;
    else return n * fact(n - 1);
  }
  ```
  - Argument n in $a0
  - Result in $v0

MIPS code:

```mips
fact:
  addi $sp, $sp, -8     # adjust stack for 2 items
  sw $ra, 4($sp)      # save return address
  sw $a0, 0($sp)      # save argument
  slti $s1, $a0, 1    # test for n < 1
  beq $s1, $zero, L1
  addi $v0, $zero, 1    # if so, result is 1
  addi $sp, $sp, 8      # pop 2 items from stack
  jr $ra # and return
L1: addi $a0, $a0, -1     # else decrement n
  jal fact             # recursive call
  lw $a0, 0($sp)      # restore original n
  lw $ra, 4($sp)      # and return address
  addi $sp, $sp, 8      # pop 2 items from stack
  mul $v0, $a0, $v0    # multiply to get result
  jr $ra # and return
```

Local Data on the Stack

- Local data allocated by callee
  - e.g., C automatic variables
  - Procedure frame (activation record)
  - Used by some compilers to manage stack storage

Memory Layout

- Text: program code
- Static data: global variables
  - e.g., static variables in C, constant arrays and strings
  - $gp initialized to address allowing offsets into this segment
- Dynamic data: heap
  - E.g., malloc in C, new in Java
- Stack: automatic storage

Character Data

- Byte-encoded character sets
  - ASCII: 128 characters
    - 95 graphic, 33 control
  - Latin-1: 256 characters
    - ASCII, 96 more graphic characters
  - Unicode: 32-bit character set
    - Used in Java, C++ wide characters, ...
    - Most of the world’s alphabets, plus symbols
    - UTF-8, UTF-16: variable-length encodings

Byte/Halfword Operations

- Could use bitwise operations
- MIPS byte/halfword load/store
  - String processing is a common case
- Sign extend to 32 bits in rt
- Zero extend to 32 bits in rt
- Store just rightmost byte/halfword

Chapter 2 — Instructions: Language of the Computer
String Copy Example

- C code (naive):
  - Null-terminated string
  ```c
  void strcpy (char x[], char y[])
  { int i;
    i = 0;
    while ((x[i]=y[i])!='\0')
      i += 1;
  }
  ```
  - Addresses of x, y in $a0, $a1
  - i in $s0

MIPS code:
```mips
strcpy:
addi $sp, $sp, -4      # adjust stack for 1 item
sw $s0, 0($sp)       # save $s0
add $s0, $zero, $zero # i = 0
L1:
  add $t1, $s0, $a1     # addr of y[i] in $t1
  lbu $t2, 0($t1)       # $t2 = y[i]
  add $t3, $s0, $a0     # addr of x[i] in $t3
  sb $t2, 0($t3)       # x[i] = y[i]
  beq $t2, $zero, L2    # exit loop if y[i] == 0
  addi $s0, $s0, 1       # i = i + 1
  j    L1                # next iteration of loop
L2: lw $s0, 0($sp)       # restore saved $s0
  addi $sp, $sp, 4       # pop 1 item from stack
  jr $ra # and return
```

32-bit Constants

- Most constants are small
  - 16-bit immediate is sufficient
- For the occasional 32-bit constant
  ```mips
  lui $t0, 61
  ori $t0, $t0, 2304
  ```

Branch Addressing

- Branch instructions specify
  - Opcode, two registers, target address
- Most branch targets are near branch
  - Forward or backward
```plaintext
<table>
<thead>
<tr>
<th>op</th>
<th>rs</th>
<th>rt</th>
<th>constant or address</th>
</tr>
</thead>
<tbody>
<tr>
<td>6 bits</td>
<td>5 bits</td>
<td>5 bits</td>
<td>16 bits</td>
</tr>
</tbody>
</table>
- PC-relative addressing
  - Target address = PC + offset × 4
  - PC already incremented by 4 by this time

Jump Addressing

- Jump (j and jal) targets could be anywhere in text segment
  - Encode full address in instruction
  ```mips
  addi $t0, $t0, -4 # adjust stack for 1 item
  sw $s0, 0($sp) # save $s0
  addi $sp, $zero, $zero # i = 0
  L1:
    add $t1, $t5, $t1 # addr of y[i] in $t1
    lbu $t2, 0($t1) # $t2 = y[i]
    add $t3, $t5, $t3 # addr of x[i] in $t3
    sb $t2, 0($t3) # x[i] = y[i]
    beq $t2, $zero, L2 # exit loop if y[i] == 0
    addi $t5, $t5, 1 # i = i + 1
    j    L1 # next iteration of loop
L2: lw $t5, 0($sp) # restore saved $s0
    addi $sp, $sp, 4 # pop 1 item from stack
    jr $ra # and return
  ```

Target Addressing Example

- Loop code from earlier example
  - Assume Loop at location 80000
```mips
Loop: sll $t1, $t3, 2 80000 0 0 19 0 9 8 9 4 0
    add $t1, $t1, $t6 80004 9 9 22 9 0 32
    lw $t0, 0($t1) 80008 9 9 8 0
    bne $t0, $t5, Exit 80012 9 9 21 19 -2
    addi $t1, $t3, 1 80016 8 19 4 1
    j    Loop 80020 2 19 -2 80000
Exit: 80024
```
Branching Far Away

- If branch target is too far to encode with 16-bit offset, assembler rewrites the code
- Example
  
  ```
  beq $s0,$s1, L1
  ↓
  bne $s0,$s1, L2
  j L1
  L2: ...
  ```

Synchronization

- Two processors sharing an area of memory
  - P1 writes, then P2 reads
  - Data race if P1 and P2 don’t synchronize
  - Result depends on order of accesses
- Hardware support required
  - Atomic read/write memory operation
  - No other access to the location allowed between the read and write
- Could be a single instruction
  - E.g., atomic swap of register ↔ memory
  - Or an atomic pair of instructions

Synchronization in MIPS

- Load linked: `ll rt, offset(rs)`
  - Succeeds if location not changed since the `ll`
  - Returns 1 in rt
- Store conditional: `sc rt, offset(rs)`
  - Fails if location is changed
  - Returns 0 in rt
- Example: atomic swap (to test/set lock variable)
  ```
  try: add $t0,$zero,$s4 ;copy exchange value
  ll $t1,0($s1)    ;load linked
  sc  $t0,0($s1)    ;store conditional
  beq $t0,$zero,try ;branch store fails
  add $s4,$zero,$t1 ;put load value in $s4
  ```

Translation and Startup

- Many compilers produce object modules directly
- Static linking

Assembler Pseudoinstructions

- Most assembler instructions represent machine instructions one-to-one
- Pseudoinstructions: figments of the assembler’s imagination
  - `move $t0, $t1` → `add $t0, $zero, $t1`
  - `blt $t0, $t1, L` → `slt $at, $t0, $t1`
  - `bne $at, $zero, L`
  - `$at` (register 1): assembler temporary
Producing an Object Module

- Assembler (or compiler) translates program into machine instructions
- Provides information for building a complete program from the pieces
  - Header: described contents of object module
  - Text segment: translated instructions
  - Static data segment: data allocated for the life of the program
  - Relocation info: for contents that depend on absolute location of loaded program
  - Symbol table: global definitions and external refs
  - Debug info: for associating with source code

Linking Object Modules

- Produces an executable image
  1. Merges segments
  2. Resolve labels (determine their addresses)
  3. Patch location-dependent and external refs
- Could leave location dependencies for fixing by a relocating loader
  - But with virtual memory, no need to do this
  - Program can be loaded into absolute location in virtual memory space

Loading a Program

- Load from image file on disk into memory
  1. Read header to determine segment sizes
  2. Create virtual address space
  3. Copy text and initialized data into memory
    - Or set page table entries so they can be faulted in
  4. Set up arguments on stack
  5. Initialize registers (including $sp, $fp, $gp)
  6. Jump to startup routine
    - Copies arguments to $a0, … and calls main
    - When main returns, do exit syscall

Dynamic Linking

- Only link/load library procedure when it is called
  - Requires procedure code to be relocatable
  - Avoids image bloat caused by static linking of all (transitively) referenced libraries
  - Automatically picks up new library versions

Lazy Linkage

Lazy linkage involves the use of an indirection table to store the addresses of library routines. When a routine is referenced, a stub is loaded, which then jumps to the linker/loader to resolve the reference. The linker/loader then resolves the reference and dynamically maps the code into the program's virtual address space.

Starting Java Applications

Java applications are started by loading a Java program that contains the main method. The JVM is started with a simple portable instruction set. The JVM then compiles bytecodes of "hot" methods into native code for the host machine. The JVM interprets bytecodes.

This process allows for efficient execution of Java programs, as the JVM can dynamically optimize and execute code as needed.
C Sort Example

- Illustrates use of assembly instructions for a C bubble sort function
- Swap procedure (leaf)
  ```c
  void swap(int v[], int k) {
    int temp;
    temp = v[k];
    v[k] = v[k+1];
    v[k+1] = temp;
  }
  ```
  
  v in $a0, k in $a1, temp in $t0

The Sort Procedure in C

- Non-leaf (calls swap)
  ```c
  void sort (int v[], int n) {
    int i, j;
    for (i = 0; i < n; i += 1) {
      for (j = i – 1; j >= 0 && v[j] > v[j + 1]; j -= 1) {
        swap(v,j);
      }
    }
  }
  ```
  
v in $a0, k in $a1, i in $s0, j in $s1

The Procedure Swap

```assembly
Swap: sll $t1, $a1, 2   # $t1 = k * 4
add $t1, $a0, $t1 # $t1 = v+(k*4)  # (address of v[k])
lw $t0, 0($t1)    # $t0 (temp) = v[k]
lw $t2, 4($t1)    # $t2 = v[k+1]
sw $t0, 0($t1)    # v[k] = $t2 (v[k+1])
sw $t2, 4($t1)    # v[k+1] = $t0 (temp)
jr $ra # return to calling routine
```

The Procedure Body

- Move params & call
  ```assembly
  move $s2, $a0           # save $a0 into $s2
  move $s3, $a1           # save $a1 into $s3
  move $s0, $zero         # i = 0
  for1tst: slt $t0, $s0, $s3      # $t0 = 0 if $s0
                                # ≥ $s3 (i ≥ n)
  beq $t0, $zero, exit1  # go to exit1 if $s0
                                # ≥ $s3 (i ≥ n)
  addi $s1, $s0, –1       # j = i – 1
  for2tst: slti $t0, $s1, 0        # $t0 = 1 if $s1 < 0 (j < 0)
  bne $t0, $zero, exit2  # go to exit2 if $s1 < 0 (j < 0)
  sll $t1, $s1, 2        # $t1 = j * 4
  add  $t2, $s2, $t1      # $t2 = v + (j * 4)
lw $t3, 0($t2)        # $t3 = v[j]
lw $t4, 4($t2)        # $t4 = v[j+1]
  slt $t0, $t4, $t3      # $t0 = 0 if $t4
                                # ≥ $t3
  beq $t0, $zero, exit2  # go to exit2 if $t4
                                # ≥ $t3
  move $a0, $s2           # 1st param of swap is v (old $a0)
  move $a1, $s1           # 2nd param of swap is j
  jal swap               # call swap procedure
  addi $s1, $s1, –1       # j –= 1
  j    for2tst            # jump to test of inner loop
  exit2:   addi $s0, $s0, 1        # i += 1
  j    for1tst            # jump to test of outer loop
  ```

The Full Procedure

```assembly
sort:    addi $sp,$sp, –20      # make room on stack for 5 registers
  sw $ra, 16($sp)        # save $ra on stack
  sw $s3,12($sp)         # save $s3 on stack
  sw $s2, 8($sp)         # save $s2 on stack
  sw $s1, 4($sp)         # save $s1 on stack
  sw $s0, 0($sp)         # save $s0 on stack
  # procedure body
  exit2:   lw $s0, 0($sp)  # restore $s0 from stack
  lw $s1, 4($sp)         # restore $s1 from stack
  lw $s2, 8($sp)         # restore $s2 from stack
  lw $s3,12($sp)         # restore $s3 from stack
  add $s0, $s0, $s1, $s2, $s3, $sp, $ra  # procedure body
  jr $ra # return to calling routine
```

Effect of Compiler Optimization

- Compiled with gcc for Pentium 4 under Linux
### Effect of Language and Algorithm

- **Bubblesort Relative Performance**
- **Quicksort Relative Performance**
- **Quicksort vs. Bubblesort Speedup**

### Lessons Learnt
- Instruction count and CPI are not good performance indicators in isolation.
- Compiler optimizations are sensitive to the algorithm.
- Java/JIT compiled code is significantly faster than JVM interpreted.
  - Comparable to optimized C in some cases.
  - Nothing can fix a dumb algorithm!

### Arrays vs. Pointers
- Array indexing involves:
  - Multiplying index by element size
  - Adding to array base address
  - Pointers correspond directly to memory addresses.
  - Can avoid indexing complexity

### Example: Clearing and Array

```c
void clear1(int array[], int size) {
    int i;
    for (i = 0; i < size; i += 1)
        array[i] = 0;
}
```

### ARM & MIPS Similarities
- ARM: the most popular embedded core
- Similar basic set of instructions to MIPS

<table>
<thead>
<tr>
<th></th>
<th>ARM</th>
<th>MIPS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Date announced</td>
<td>1985</td>
<td>1985</td>
</tr>
<tr>
<td>Instruction size</td>
<td>32 bits</td>
<td>32 bits</td>
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<tr>
<td>Address space</td>
<td>32-bit flat</td>
<td>32-bit flat</td>
</tr>
<tr>
<td>Data alignment</td>
<td>Aligned</td>
<td>Aligned</td>
</tr>
<tr>
<td>Data addressing modes</td>
<td>9</td>
<td>3</td>
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<tr>
<td>Registers</td>
<td>$15 \times 32$-bit</td>
<td>$31 \times 32$-bit</td>
</tr>
<tr>
<td>Input/output</td>
<td>Memory mapped</td>
<td>Memory mapped</td>
</tr>
</tbody>
</table>
Chapter 2 — Instructions: Language of the Computer

Compare and Branch in ARM

- Uses condition codes for result of an arithmetic/logical instruction
  - Negative, zero, carry, overflow
  - Compare instructions to set condition codes without keeping the result
- Each instruction can be conditional
  - Top 4 bits of instruction word: condition value
  - Can avoid branches over single instructions

Instruction Encoding

The Intel x86 ISA

- Evolution with backward compatibility
  - 8080 (1974): 8-bit microprocessor
    - Accumulator, plus 3 index-register pairs
  - 8086 (1978): 16-bit extension to 8080
    - Complex instruction set (CISC)
  - 8087 (1980): floating-point coprocessor
    - Adds FP instructions and register stack
  - 80286 (1982): 24-bit addresses, MMU
    - Segmented memory mapping and protection
  - 80386 (1985): 32-bit extension (now IA-32)
    - Additional addressing modes and operations
    - Paged memory mapping as well as segments

The Intel x86 ISA

- Further evolution...
  - i486 (1989): pipelined, on-chip caches and FPU
  - Pentium (1993): superscalar, 64-bit datapath
    - Later versions added MMX (Multi-Media eXtension) instructions
    - The infamous FDIV bug
    - New microarchitecture (see Colwell, The Pentium Chronicles)
  - Pentium III (1999)
    - Added SSE (Streaming SIMD Extensions) and associated registers
  - Pentium 4 (2001)
    - New microarchitecture
    - Added SSE2 instructions

The Intel x86 ISA

- And further...
  - AMD64 (2003): extended architecture to 64 bits
  - EM64T – Extended Memory 64 Technology (2004)
  - AMD64 adopted by Intel (with refinements)
    - Added SSE3 instructions
  - Intel Core (2006)
    - Added SSE4 instructions, virtual machine support
  - AMD64 (announced 2007): SSE5 instructions
    - Intel declined to follow, instead
    - Advanced Vector Extension (announced 2008)
      - Longer SSE registers, more instructions
      - If Intel didn’t extend with compatibility, its competitors would!
    - Technical elegance ≠ market success

Basic x86 Registers
Basic x86 Addressing Modes

- Two operands per instruction
  - First operand
    - Source/dest operand
    - Register
    - Memory
    - Immediate
  - Second operand
    - Register
    - Memory
    - Immediate

- Memory addressing modes
  - Address in register
  - Address = Rbase + displacement
  - Address = Rbase + 2^{scale} × Rindex (scale = 0, 1, 2, or 3)
  - Address = Rbase + 2^{scale} × Rindex + displacement

x86 Instruction Encoding

- Variable length encoding
  - Postfix bytes specify addressing mode
  - Prefix bytes modify operation
    - Operand length, repetition, locking, ...

Implementing IA-32

- Complex instruction set makes implementation difficult
  - Hardware translates instructions to simpler microoperations
    - Simple instructions: 1–1
    - Complex instructions: 1–many
  - Microengine similar to RISC
  - Market share makes this economically viable

- Comparing performance to RISC
  - Compilers avoid complex instructions

Fallacies

- Backward compatibility ⇒ instruction set doesn’t change
  - But they do accrete more instructions

- Complex instruction set makes implementation difficult
  - Hardware translates instructions to simpler microoperations
    - Simple instructions: 1–1
    - Complex instructions: 1–many
  - Microengine similar to RISC
  - Market share makes this economically viable

- Comparing performance to RISC
  - Compilers avoid complex instructions

Pitfalls

- Sequential words are not at sequential addresses
  - Increment by 4, not by 1!
- Keeping a pointer to an automatic variable after procedure returns
  - e.g., passing pointer back via an argument
  - Pointer becomes invalid when stack popped
Concluding Remarks

- Design principles
  1. Simplicity favors regularity
  2. Smaller is faster
  3. Make the common case fast
  4. Good design demands good compromises
- Layers of software/hardware
  - Compiler, assembler, hardware
- MIPS: typical of RISC ISAs
  - c.f. x86

Measure MIPS instruction executions in benchmark programs
- Consider making the common case fast
- Consider compromises

<table>
<thead>
<tr>
<th>Instruction class</th>
<th>MIPS examples</th>
<th>SPEC2006 Int</th>
<th>SPEC2006 FP</th>
</tr>
</thead>
<tbody>
<tr>
<td>Arithmetic</td>
<td>add, sub, addi</td>
<td>16%</td>
<td>48%</td>
</tr>
<tr>
<td>Data transfer</td>
<td>lw, sw, lb, lbu, lh, lhu, sb, lsl</td>
<td>35%</td>
<td>36%</td>
</tr>
<tr>
<td>Logical</td>
<td>and, or, nor, andi, ori, sll, srli</td>
<td>12%</td>
<td>4%</td>
</tr>
<tr>
<td>Cond. Branch</td>
<td>beq, bne, slt, slti, sltiu</td>
<td>34%</td>
<td>8%</td>
</tr>
<tr>
<td>Jump</td>
<td>j, jr, jal</td>
<td>2%</td>
<td>0%</td>
</tr>
</tbody>
</table>